

# Tung Do

M.Sc. ECE – Robotics candidate | Research Assistant | University of Michigan, Ann Arbor | Seeking Summer 2024 Internship  
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## EDUCATION

<b>University of Michigan, Ann Arbor</b> <i>Candidate for Master of Science in Electrical and Computer Engineering, Robotics area</i> <ul style="list-style-type: none"><li>Coursework: Self-driving Cars, Embedded Control System, Math for Robotics (Fall 2023) Machine Learning, Deep Learning for Computer Vision, Reinforcement Learning (Winter 2024)</li><li>Cumulative GPA: 4.0/4.0. Member of the Institute of Electrical and Electronics Engineers.</li></ul>	Aug 2023 – May 2025 Ann Arbor, MI
<b>California State Polytechnic University, Pomona</b> <i>Bachelor of Science, magna cum laude, in Electromechanical Systems Engineering Technology - Valedictorian</i> <ul style="list-style-type: none"><li>Cumulative GPA: 3.7/4.0. Member of Tau Beta Pi – The Engineering Honor Society.</li></ul>	Aug 2018 – May 2023 Pomona, CA

## PROFESSIONAL EXPERIENCE

<b>Research Assistant/Embedded Systems Engineer</b> <i>TD-Rex Rover Research in ROAHM Lab at the University of Michigan, Ann Arbor</i> <ul style="list-style-type: none"><li>Working on speeding up the segmented camera stream for the research's machine learning model using ROS C++, OpenCV, and Rviz.</li><li>Integrating the MPC model for the new rover using ROS C++.</li><li>Programmed embedded control on STM32 VESC and Jetson TX2's Linux environment for a new Autonomous Rover.</li></ul>	Aug 2023 – Present Ann Arbor, MI
<b>Embedded Systems Engineer</b> <i>Northrop Grumman Collaboration Project 2022-2023</i> <ul style="list-style-type: none"><li>Successfully launched autonomous flight, keeping the Unmanned Aerial Vehicle (UAV) in the air at 200ft height from the ground for 20-minute flights, by developing Python scripts on Jetson Nano's Linux environment and uploading the mission to the Pixhawk.</li><li>Integrated ROS Python and programmed STM32 MCU using Embedded C to communicate two Raspberry Pi for the Unmanned Ground Vehicle (UGV).</li><li>Gave a presentation about our work in the Preliminary Design Review meeting at the Northrop Grumman facility in Palmdale, CA.</li></ul>	Aug 2022 – May 2023 Pomona, CA
<b>Embedded Software Engineer Intern</b> <i>FPT USA Corp.</i> <ul style="list-style-type: none"><li>Developed streaming platform for Roku device using BrightScript language and SceneGraph library.</li></ul>	May 2022 – Aug 2022 El Segundo, CA
<b>Software Developer Intern</b> <i>Rakuna (during COVID-19)</i> <ul style="list-style-type: none"><li>Developed Rakuna's Recruiting website, using Ruby on Rails, ReactJS, HTML/CSS, SQL, and RESTFUL API.</li></ul>	May 2021 – Jul 2021 Hanoi, Vietnam

## PROJECTS

<b>FPGA Projects   Project Owner</b> <ul style="list-style-type: none"><li>Compiling/Developing a complete FPGA development toolchain for MacOS CLI users.</li><li>Developed Verilog code for I2C communication between an FPGA and a current sensor, including a clock signal synchronizing data transfer between devices.</li><li>Integrated a PMOD display into the system to provide real-time monitoring of current readings of the phone under charge.</li></ul>	Jan 2023 – May 2023
<b>Autonomous Robot Competition   Lead Engineer</b> <ul style="list-style-type: none"><li>Won 2nd place in the competition using C, C++, Python, OpenCV on Raspberry Pi, and STM32 MCU.</li><li>The robot was praised as the best and most stable performance throughout the competition. The hardware never had any issues.</li><li>Administered weekly meetings to check progress, give feedback, test more than 200 times, and assign new tasks to 6 team members.</li></ul>	Aug 2022 – Dec 2022
<b>Autonomous/RC Mecanum Wheel Tesla Roadster 1:6   Project Owner</b> <ul style="list-style-type: none"><li>Successfully developed wireless control/automatic features on the vehicle with 6 Arduinos communicating with each other through NRF24L01 radio modules within a range of 160ft, and developed autonomous functions, including self-parking and object avoidance, using C, C++.</li></ul>	Jan 2022 – Dec 2022

## SKILLS

Robotics:	ROS, Rviz, Gazebo, OpenCV, NumPy, Pandas
Languages:	C, C++, Python, Java, Verilog, MATLAB, Bash/Shell Scripting
Hardware:	Linux, MCU, SBC, FPGA, x86, arch, ARM, RISC-V, I2C, SPI, USART, USB, RTOS, Debugger IDE, Vim, CLI, Git, Simulink
CAD:	SolidWorks, 3D Printer, Ansys